



# Application of AtoN Telematics for Structural Health Monitoring

Aivar Usk, Cybernetica AS

Per Erik Ose, Norwegian Coastal Administration

Leif Arne Larsen, Norwegian Coastal Administration

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# Problem

- ⊙ Structural stability of certain types of fixed AtoN platforms is degrading at less predictable rate than others
- ⊙ Stability of lattice masts and seabed-embedded poles is subject to degradation due to wind and wave effects
- ⊙ **Cases of fixed AtoN platforms collapsing under wind or wave load, or introducing permanent focal plane inclination / misalignment of leading line centerline due to material degradation are not too rare**
- ⊙ Restoration of a collapsed AtoN tends to be costly while safety of navigation is at least temporarily compromised

# Solution

- ⊙ Responding with slight deflection to external excitations like incident wind gusts and waves, slender pole-like structures tend to **vibrate at clearly defined natural frequencies** that shift when mechanical properties of the structure change (loose bolts or tensioners, weight loss)
- ⊙ That effect presents opportunities for two-tiered structural health monitoring of AtoN platforms:
  - ⊙ Monitoring of the **vibration magnitude** to estimate severity of conditions and detect trends like increasing deflections
  - ⊙ Monitoring of the **frequency** of the dominating spectral component in order to detect mechanical changes

# Natural Frequency Appears When Excited



The resonance frequency depends on mass, stiffness and damping: dimensions, materials, weight, temperature, etc

# Applicable Technologies

- ⊙ **Structural Health Monitoring (SHM)** is nothing new
- ⊙ Optimal for use on AtoN: an in-situ **acceleration sensor**
- ⊙ **Analysis of vibration spectra using the Fast Fourier Transform (FFT)** may require too much **power** locally; it can be performed automatically at the server side after uploading the acceleration data from an AtoN site
- ⊙ Cost savings come from tasking the **AtoN telematics infrastructure** with additional monitoring mission

# Cybernetica AtoN SHM Solution

- ⊙ Based on existing AtoN Telematics Controller **TelFiCon™** that uses a triaxial solid state acceleration sensor
- ⊙ In-situ **acceleration measurement with local inclination angle calculation and raw data upload** to the telematics server since 2008 (GSM/GPRS/3G)
- ⊙ Widely configurable measurement mission profile: from 1 minute hourly sessions to continuous acceleration measurement at **20 ms sampling interval**
- ⊙ Temperature and voltage measurement as standard, AtoN **flasher functionality supporting FFI** is available

# NCA01: Dirigens Lux AtoN at Småge

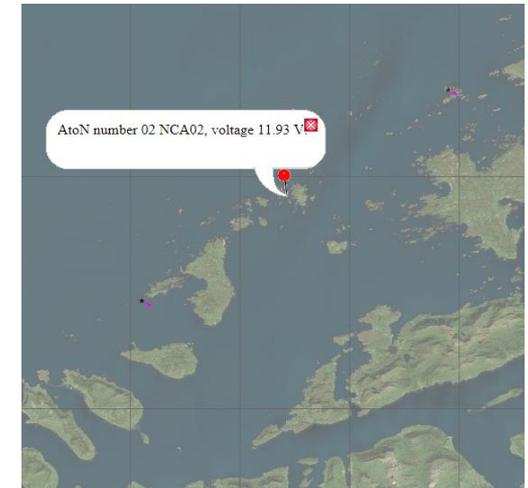
- ⊙ Height 7.5 m above sea level, 2 m under water (high tide)
- ⊙ Weight 100 kg
- ⊙ Mount: embedded in seabed (or rock)
- ⊙ Bearing structure: Ø 140 mm composite rod
- ⊙ Type: Test object for a new maintenance free large composite HIB AtoN design



# NCA02: Dirigens Mini AtoN at Sandøy



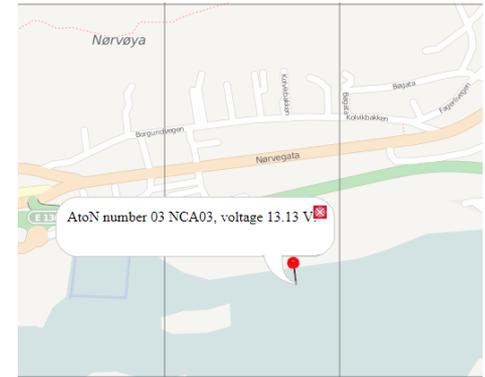
- ⊙ Height 6.5 m above sea level, 0.5 m below (high tide)
- ⊙ Weight 60 kg
- ⊙ Mount: embedded in seabed (or rock)
- ⊙ Bearing structure: Ø 140 mm composite rod
- ⊙ Type: Test object for a new maintenance free small composite HIB AtoN



# NCA03: Original HIB AtoN at Nørve



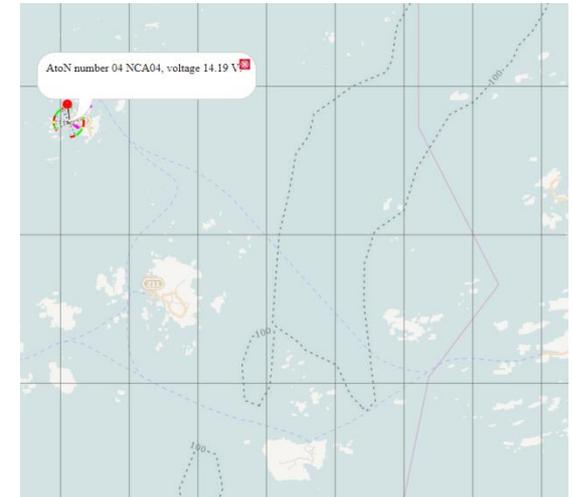
- ⊙ Height 8.5 m above sea level, 1.5 m below at high tide
- ⊙ Weight 500 kg
- ⊙ Mount: embedded in seabed (or rock)
- ⊙ Bearing structure: Ø 140 mm steel rod
- ⊙ Type: Test object for the initial HIB design, large metal structure



# NCA04: Lighthouse at Husøyvågen, Ona



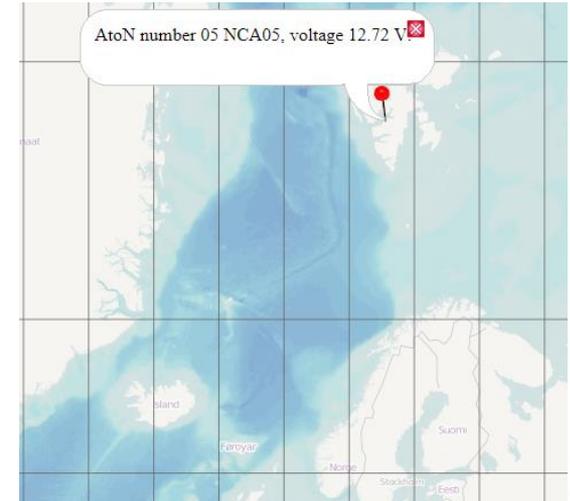
- ⊙ Height 8 m above ground
- ⊙ Weight 1500 kg
- ⊙ Mount: 4 x threaded rods 48x1000 VZN
- ⊙ Bearing structure: Composite GRP



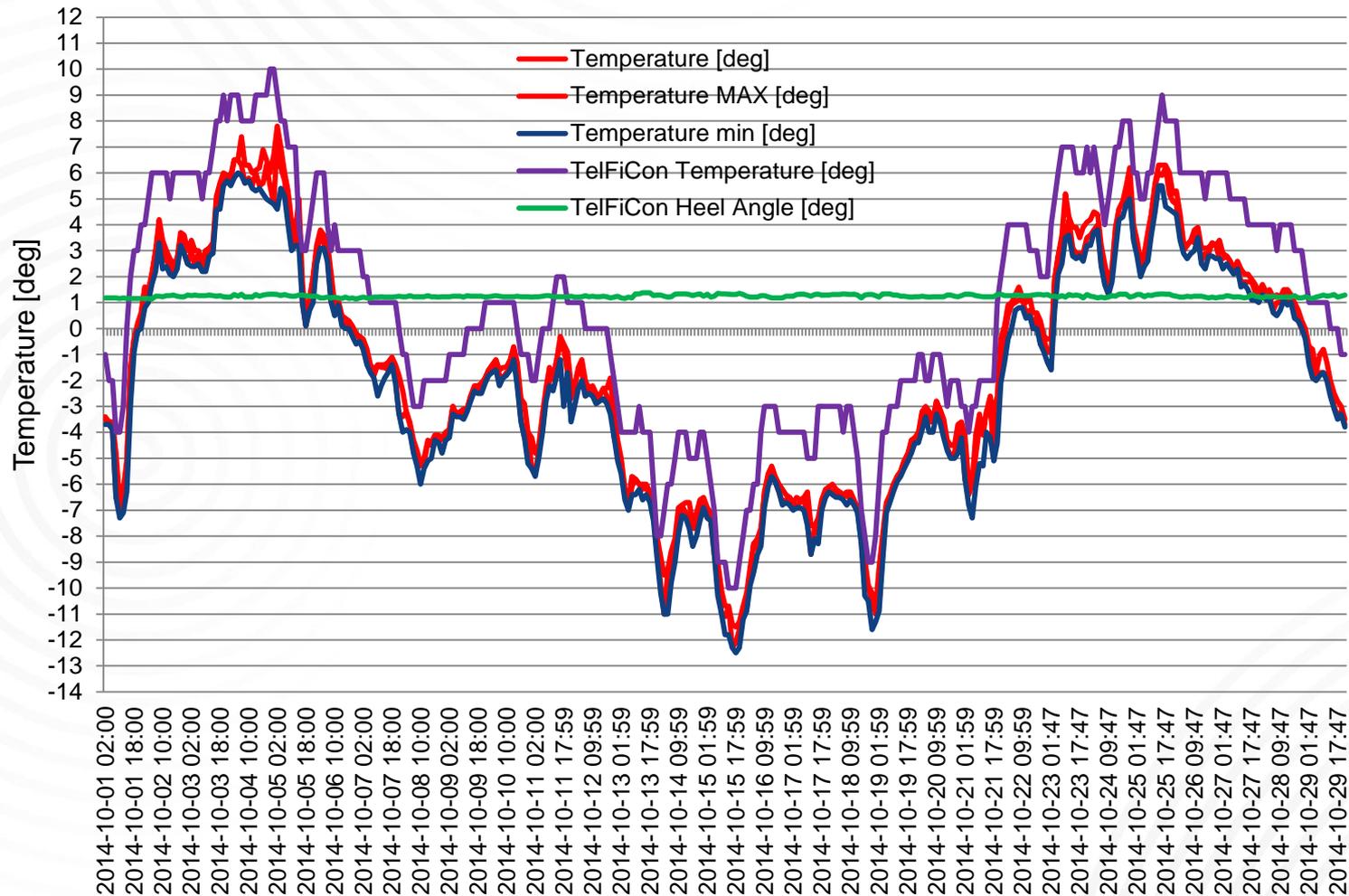
# NCA05: Litus Lux Lighthouse on Svalbard



- ⊙ Height 6.5 m
- ⊙ Weight 500 kg
- ⊙ Mount: 4 threaded rods 48x1000 VZN
- ⊙ Bearing structure: Ø 800 mm Glass fiber reinforced vinylester with a core of Divyncell
- ⊙ Type: Test object for a new maintenance free generation of composite Lighthouses



# NCA05: Litus Lux Lighthouse Environment



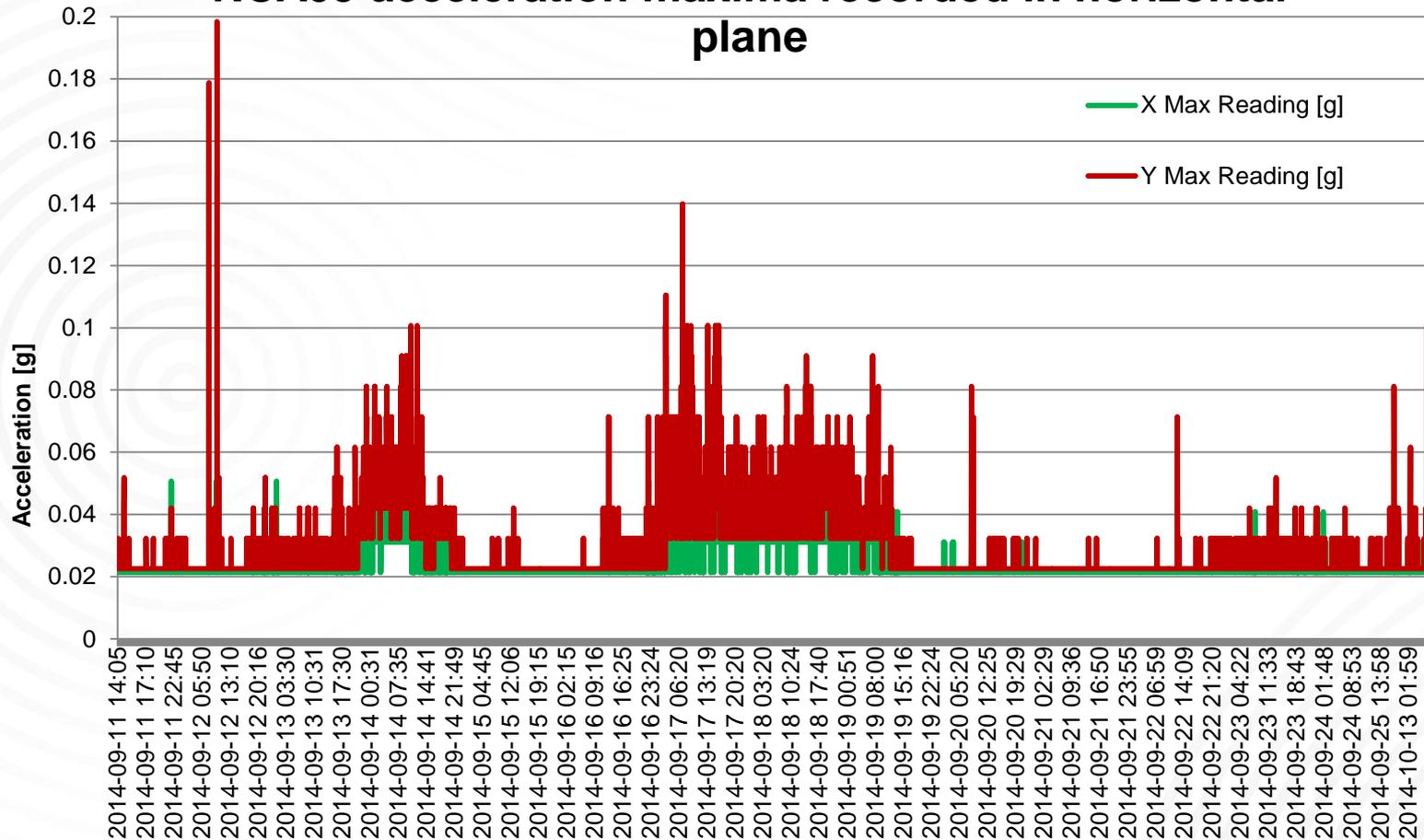
Inclination changes at  $1.25^\circ$  average are insignificant, within measurement uncertainty

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# NCA05: Litus Lux Lighthouse Acceleration

NCA05 acceleration maxima recorded in horizontal plane



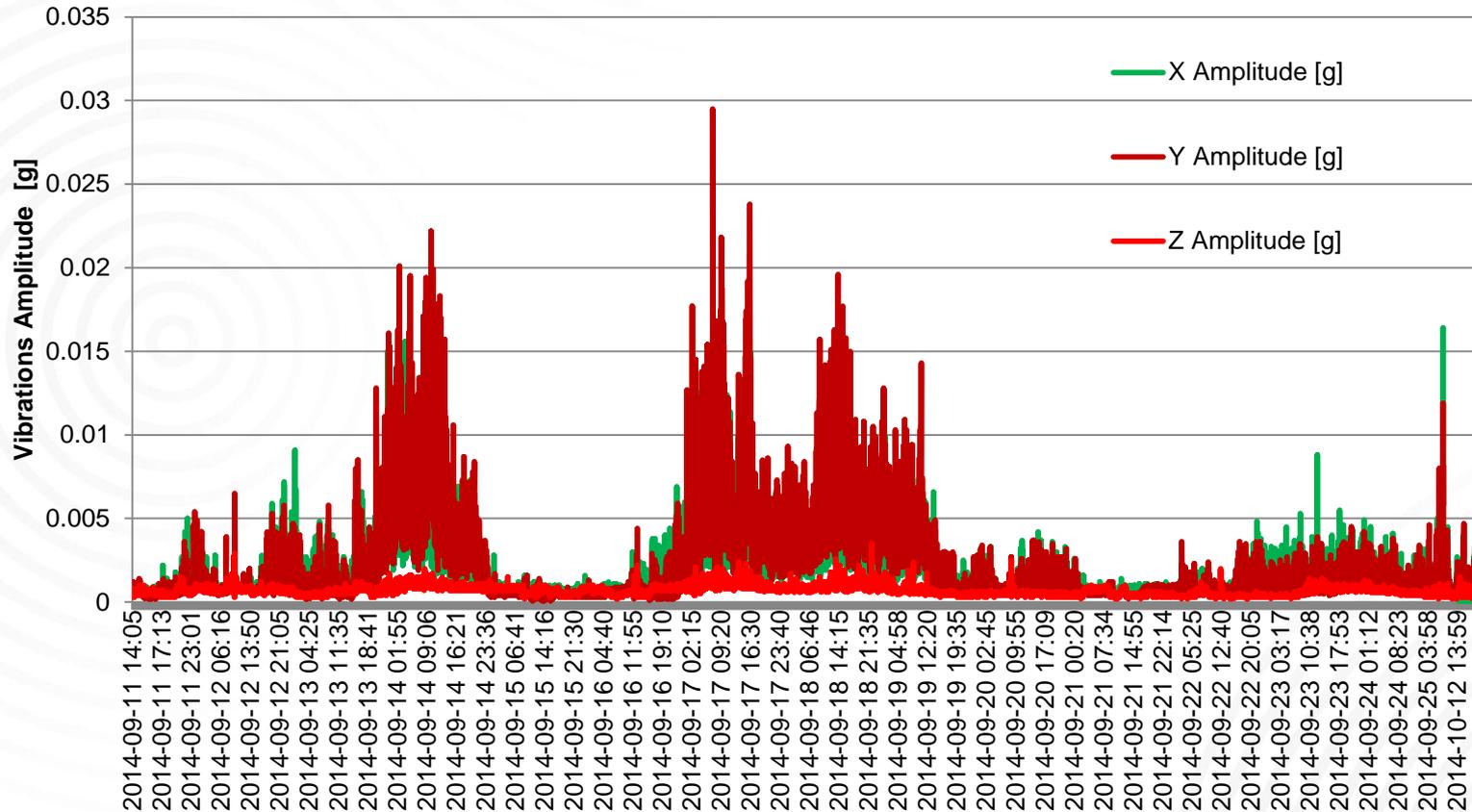
Incident wind gusts cause deflections of even stiff structures, up to 0.2g for NCA05

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# NCA05: Litus Lux Lighthouse Vibrations

NCA05 dominating vibration spectra component RMS amplitudes calculated for all axes



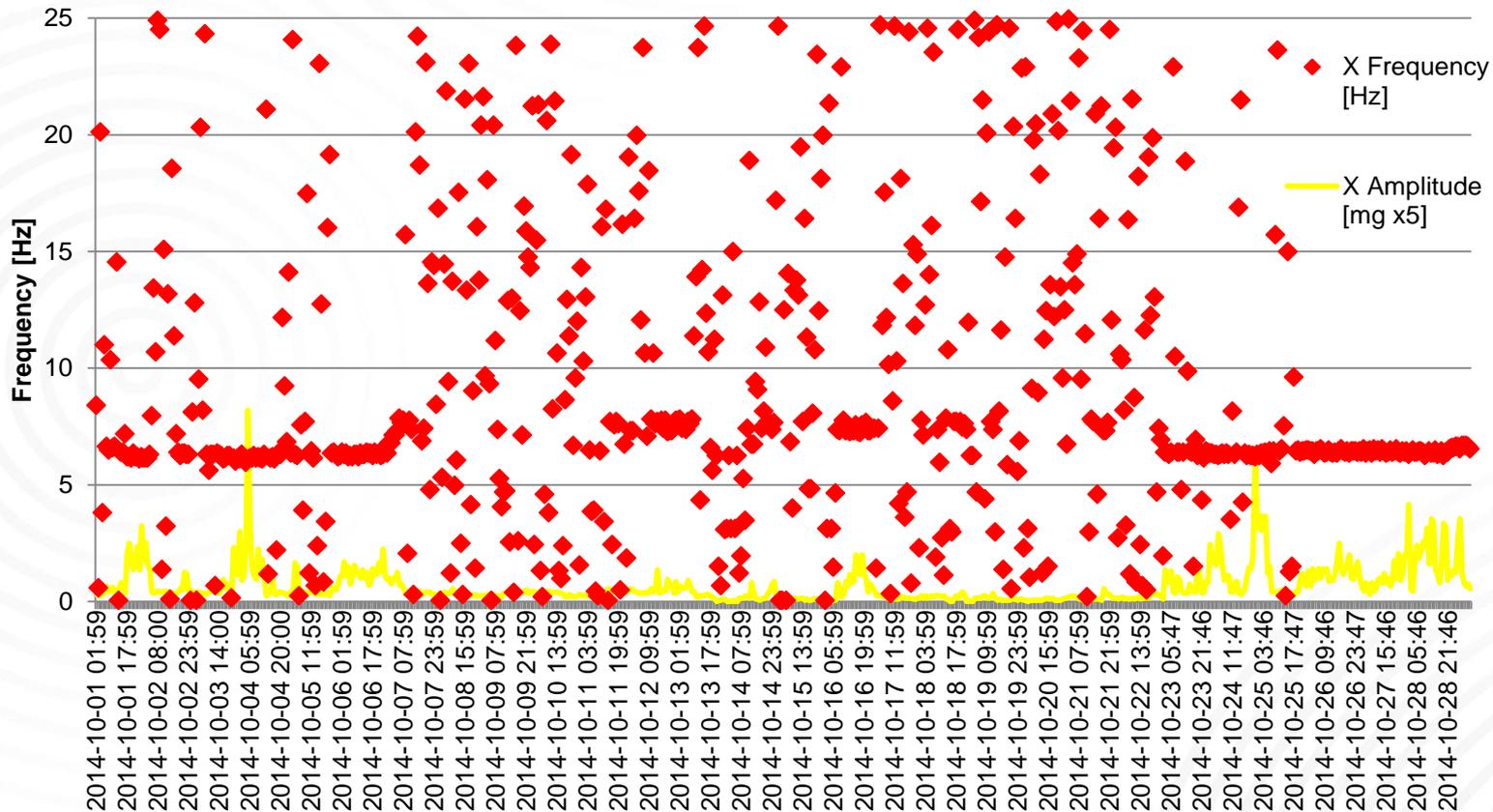
Resulting wind induced vibrations are clearly detectable and in correlation with weather data

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# NCA05: Litus Lux Natural Frequency

## X-Axis vibration frequency and magnitude (RMS)

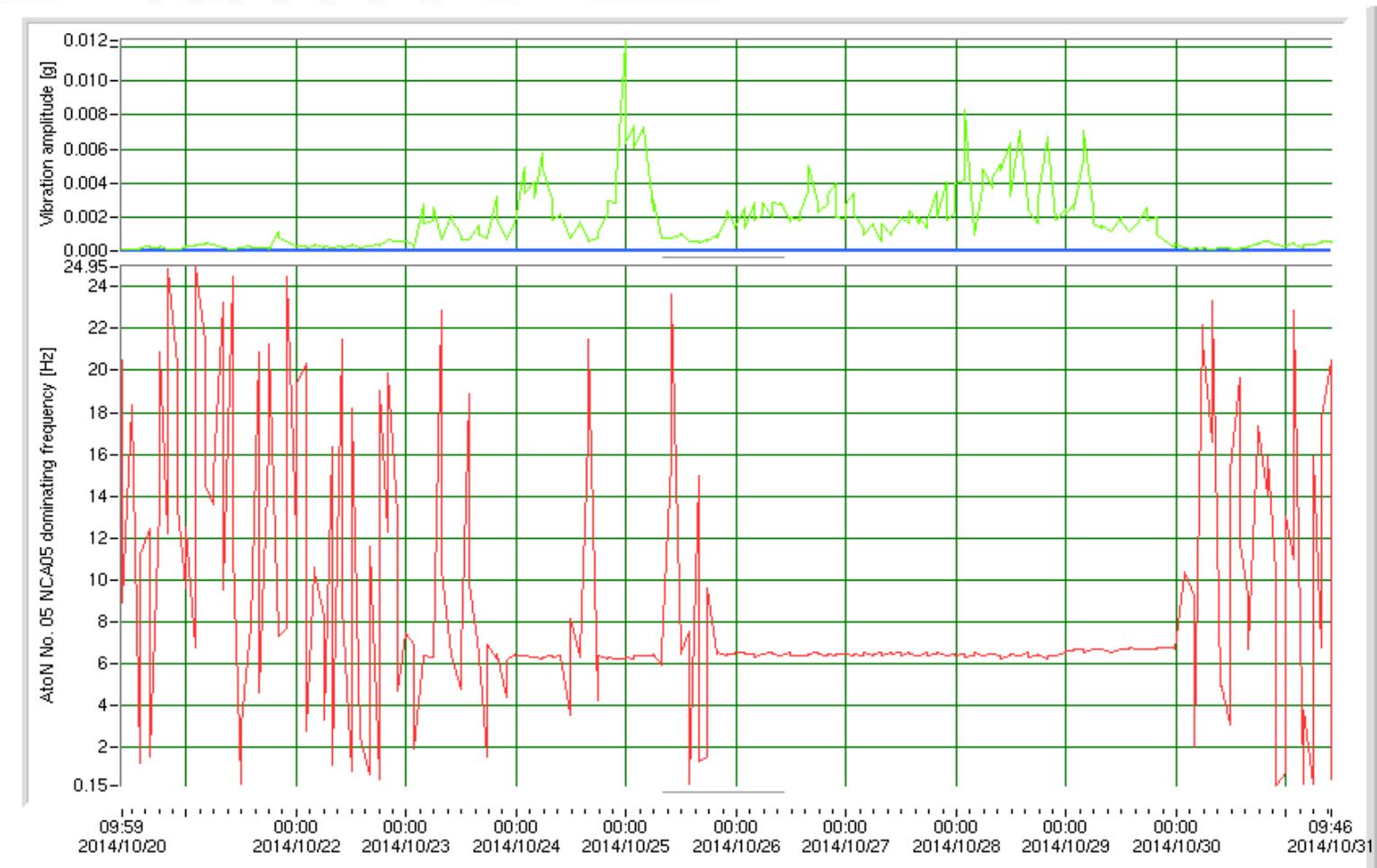


Natural frequency  $\sim 7$  Hz manifests itself when external excitation exceeds certain threshold

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# NCA05: Vibration Amplitude & Frequency

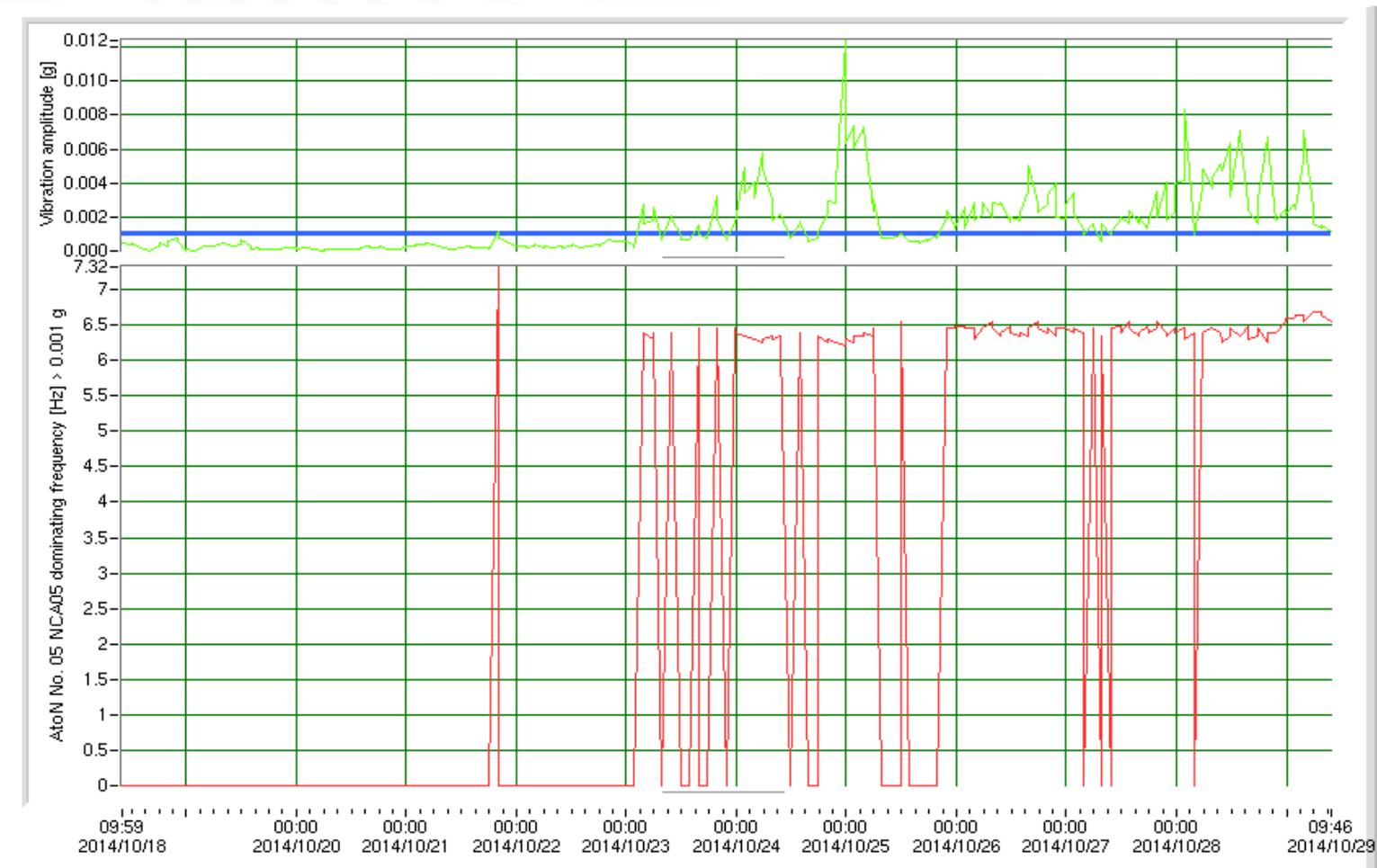


Looking at nearly 2 months of dominant frequency (X) using FFT reveals very little changes

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# NCA05: Vibration Amplitude & Frequency



Setting a 1 mg threshold for displaying the results cleans away irrelevant noise at quiet times

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# NCA05: Vibration Amplitude & Frequency



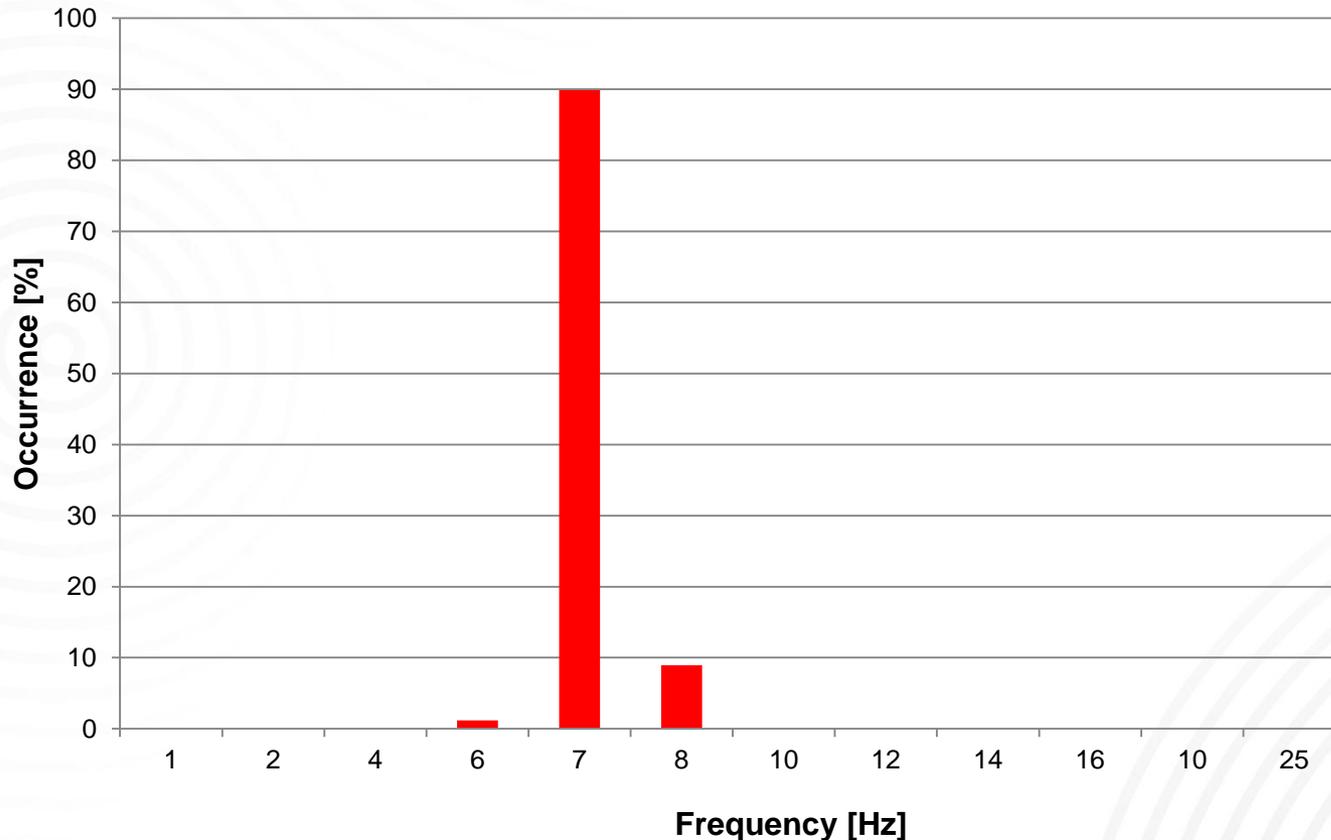
Setting a 2 mg threshold for displaying the results reveals NCA05 natural frequency trends

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# NCA05: Litus Lux Frequency Statistics

Statistical distribution of dominating frequency at the X-axis of NCA05, instances above 2 mg threshold [%]



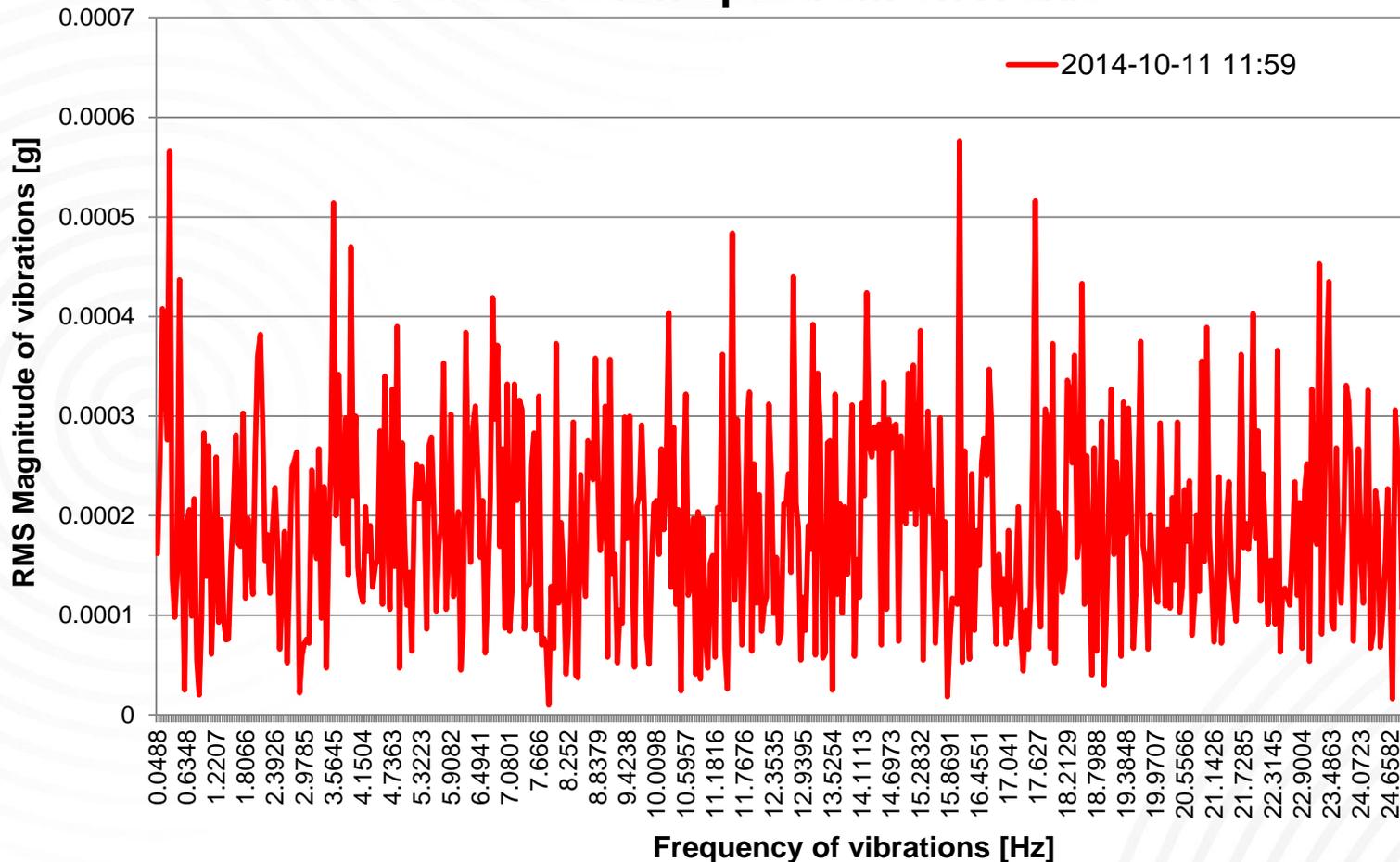
In nearly 2 months the dominant frequency was rarely detected outside typical bins

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# NCA05: Litus Lux Acceleration Spectrum

## NCA05 acceleration spectrum on X axis



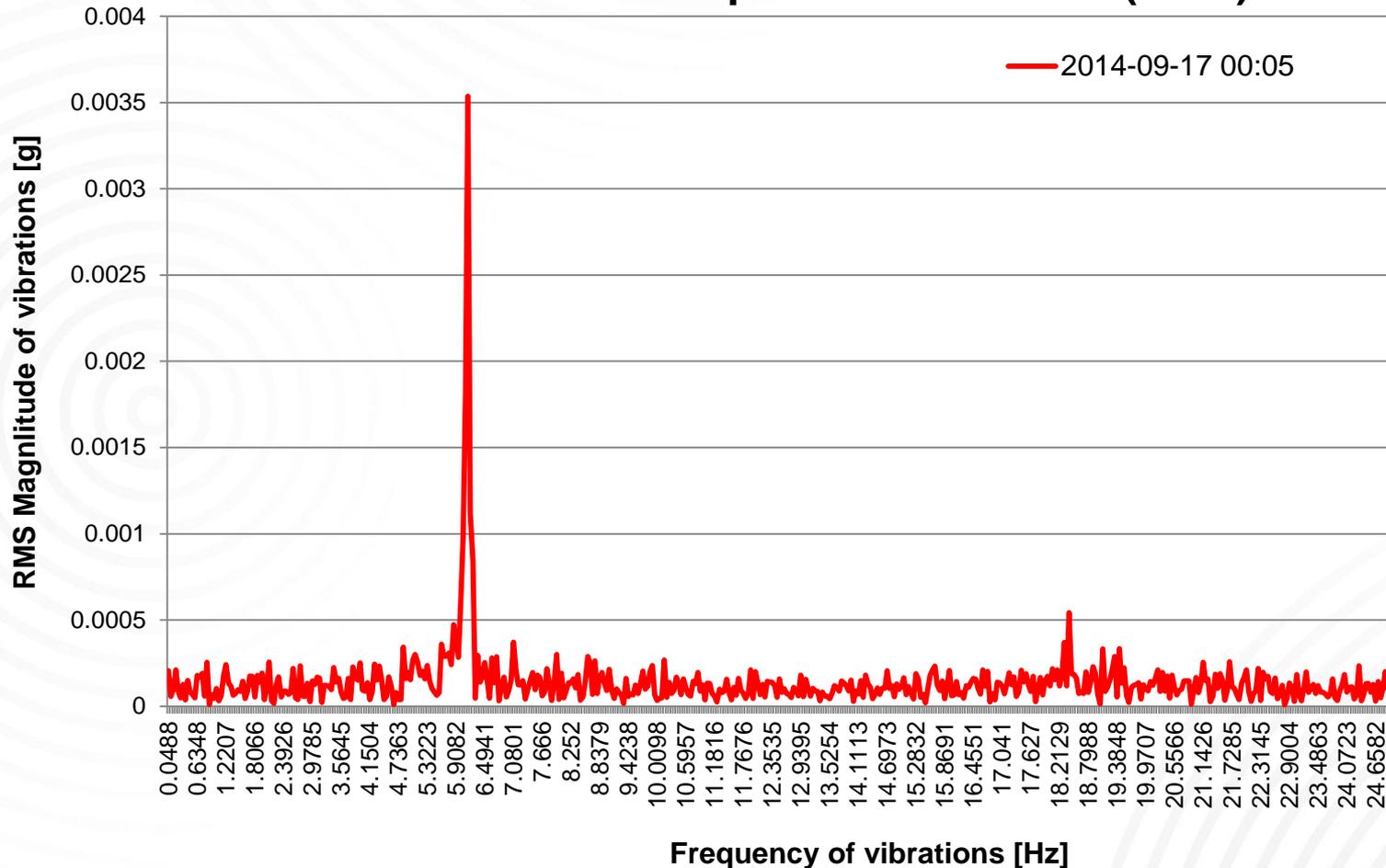
Frequency content of FFT analysis: **noise** (light air, southwest 1.2 m/s, gusts 1.8 m/s, -1.2°C)

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# NCA05: Litus Lux Acceleration Spectrum

## NCA05 acceleration spectrum on X axis (RMS)



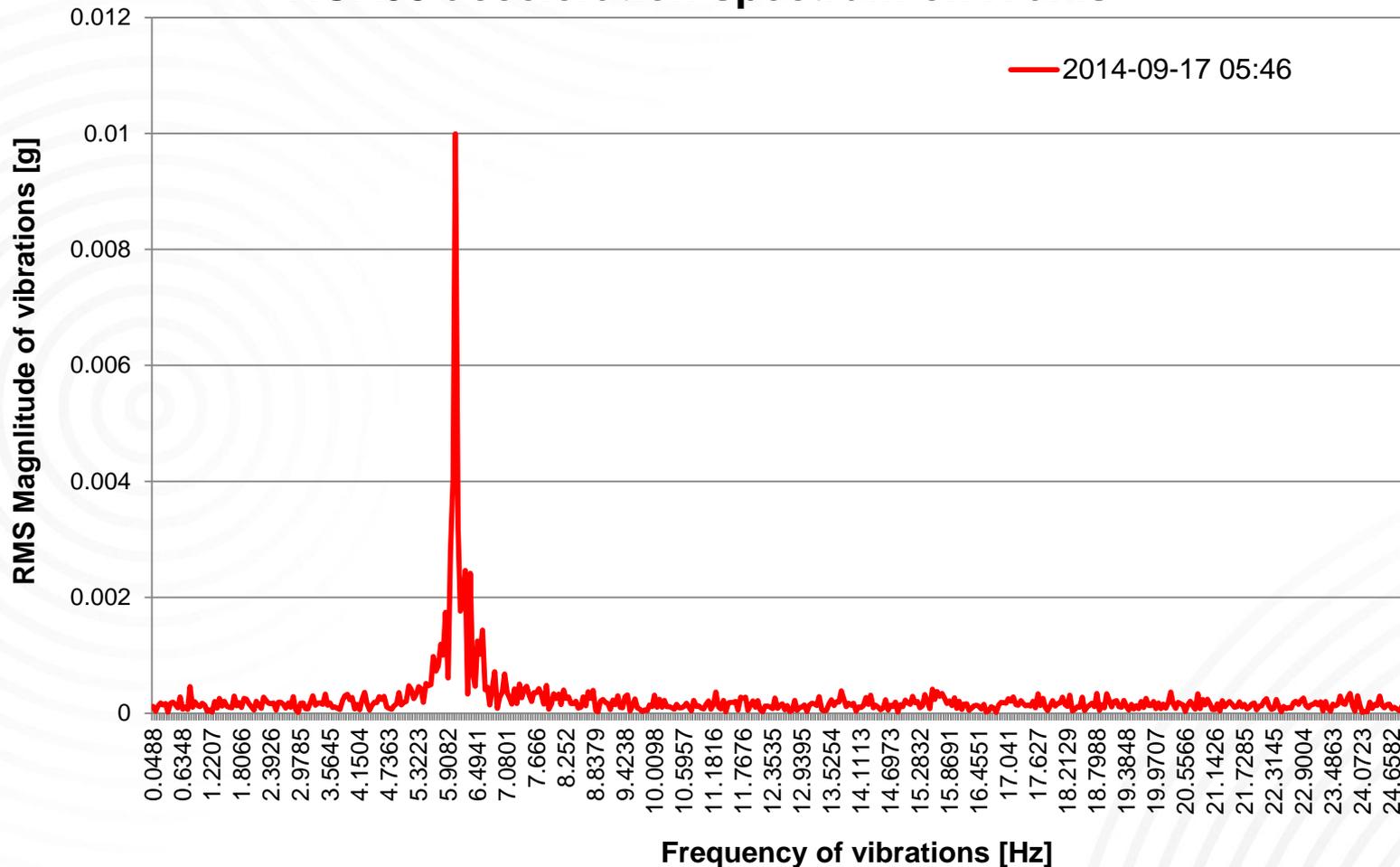
Frequency: **6.1523 Hz** (fresh southwest breeze 9.2 m/s, gusts 13.2 m/s, 6.1°C)

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# NCA05: Litus Lux Acceleration Spectrum

## NCA05 acceleration spectrum on X axis

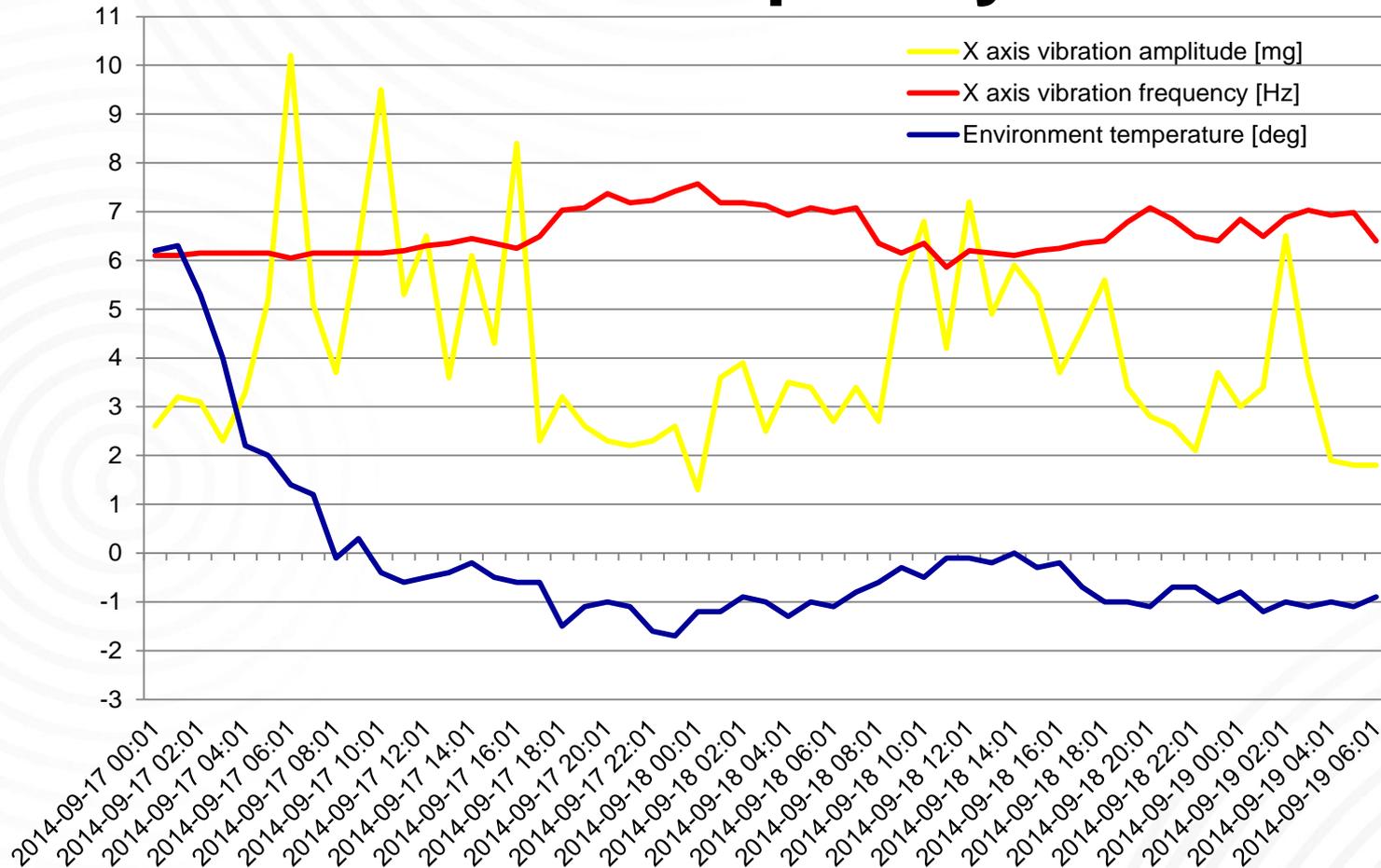


Frequency: **6.0547 Hz** (strong west-southwest breeze 11.5 m/s, gusts 15.9 m/s, 1.4°C)

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# NCA05: Natural Frequency Drift in Cold



While typical results for NCA05 natural frequency analysis averaged around **6.15 Hz** at positive temperatures, it increased to **6.69 Hz** in above case and even **7.4 Hz** below **-10°C**

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# User Interface in Web Browser (PDA)

195.50.202.195



## Kystverket-Cyber TeViNSA™ LSC AtoN Telematics Server 2.11

Site Name	Last Session	Voltage [V]	Heel Angle [deg]	Position	Script	Vibration X   Y   Z
<a href="#">NCA01</a>	2014-11-06 10:53:29	<a href="#">12.95</a>	<a href="#">3.0</a>	<a href="#">On-site</a> <a href="#">T</a>	<a href="#">Accel_Meas_Custom (20:4)</a>	<a href="#">17</a>   <a href="#">8</a>   <a href="#">1</a>
<a href="#">NCA02</a>	2014-11-06 10:51:46	<a href="#">12.54</a>	<a href="#">1.9</a>	<a href="#">On-site</a> <a href="#">T</a>	<a href="#">Accel_Meas_Custom (20:4)</a>	<a href="#">4</a>   <a href="#">5</a>   <a href="#">1</a>
<a href="#">NCA03</a>	2014-11-06 10:51:49	<a href="#">14.15</a>	<a href="#">0.3</a>	<a href="#">On-site</a> <a href="#">T</a>	<a href="#">Accel_Meas_Custom (20:4)</a>	<a href="#">3</a>   <a href="#">3</a>   <a href="#">2</a>
<a href="#">NCA04</a>	2014-11-06 10:54:11	<a href="#">14.21</a>	<a href="#">1.4</a>	<a href="#">On-site</a> <a href="#">T</a>	<a href="#">Accel_Meas_Custom (20:4)</a>	<a href="#">0</a>   <a href="#">1</a>   <a href="#">1</a>
<a href="#">NCA05</a>	2014-11-06 09:59:16	<a href="#">12.72</a>	<a href="#">1.3</a>	<a href="#">On-site</a> <a href="#">T</a>	<a href="#">Accel_Meas_Custom (20:119)</a>	<a href="#">0</a>   <a href="#">2</a>   <a href="#">1</a>

Page refresh time: 06.11.2014 at 10:55:16 UTC+1

Server started at: 22.10.2014 at 14:34:10

[Server logfile](#) [Alarms logfile](#) [Heel angle and temperature logfile](#) [Last position of all AtoNs](#)

[TLSC setup](#)



# Measurement Results, September/October

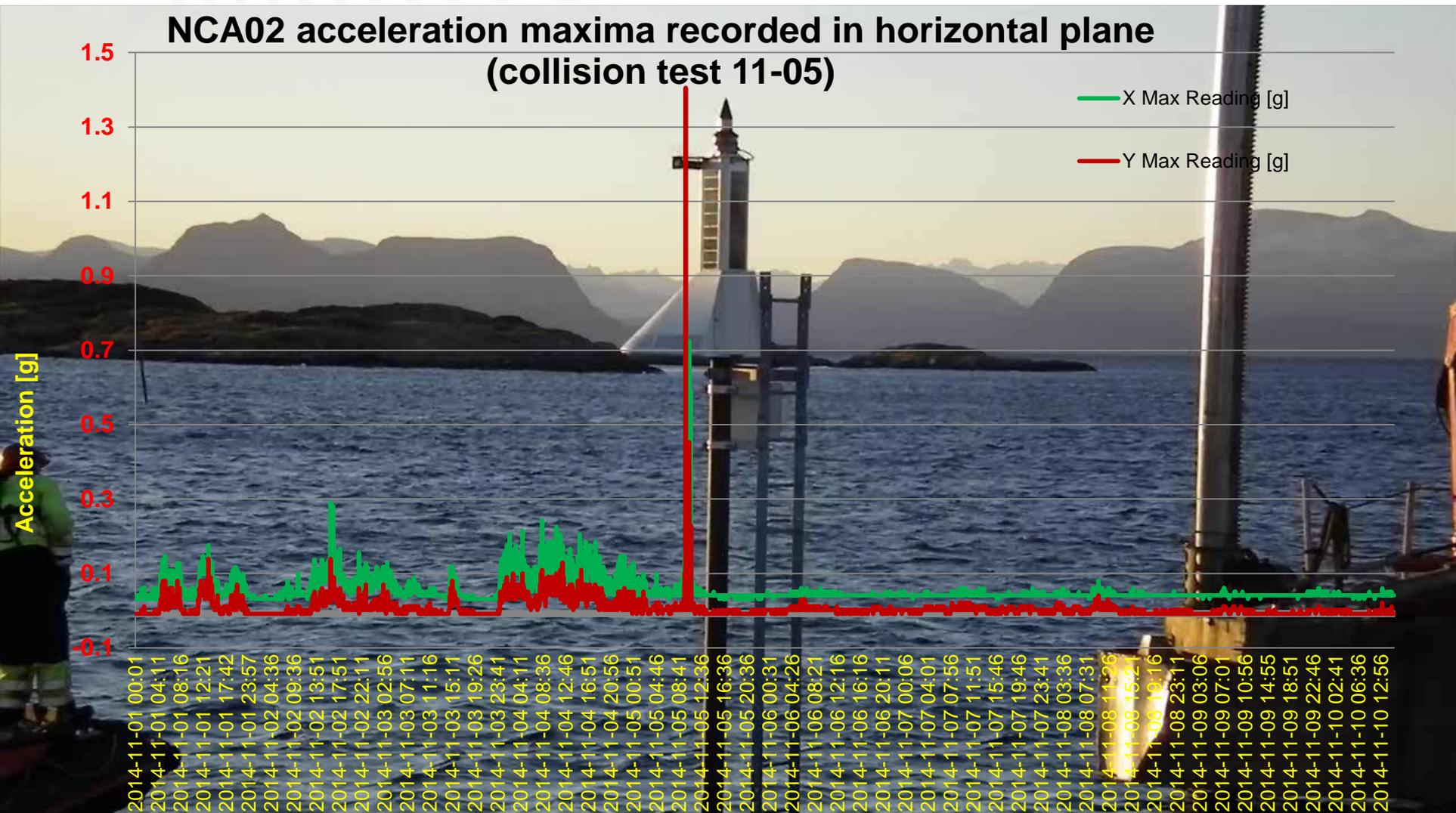
AtoN ID	AtoN Type	Natural Frequency, X-axis [Hz]	Natural Frequency, Y-axis [Hz]	Peak Vibration Magnitude, X-axis [g]	Peak Vibration Magnitude, Y-axis [g]	Peak Acceleration, X-axis [g]	Peak Acceleration, Y-axis [g]	Maximum Inclination Angle Difference [°]
NCA01	Dirigens Lux, 100 kg	<b>0.68</b>	<b>0.68</b>	0.141	0.119	0.423	0.324	1.92
NCA02	Dirigens Mini, 60 kg	<b>1.66</b>	<b>1.51</b>	0.095	0.750	1.061	1.395	1.88
NCA03	Original HIB, 500 kg	<b>0.59</b>	<b>0.59</b>	0.094	0.095	0.221	0.266	2.33
NCA04	Standard composite lighthouse, 1500 kg	<b>5.96</b>	<b>5.18</b>	0.097	0.147	0.453	0.488	0.84
NCA05	Litus Lux composite lighthouse, 500 kg	<b>6.15</b>	<b>5.86</b>	0.016	0.030	0.129	0.198	0.24

All types of fixed AtoN subject to SHM testing by TelFiCon™ units provided meaningful data

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# Collision Test on NCA02 on 2014-11-05

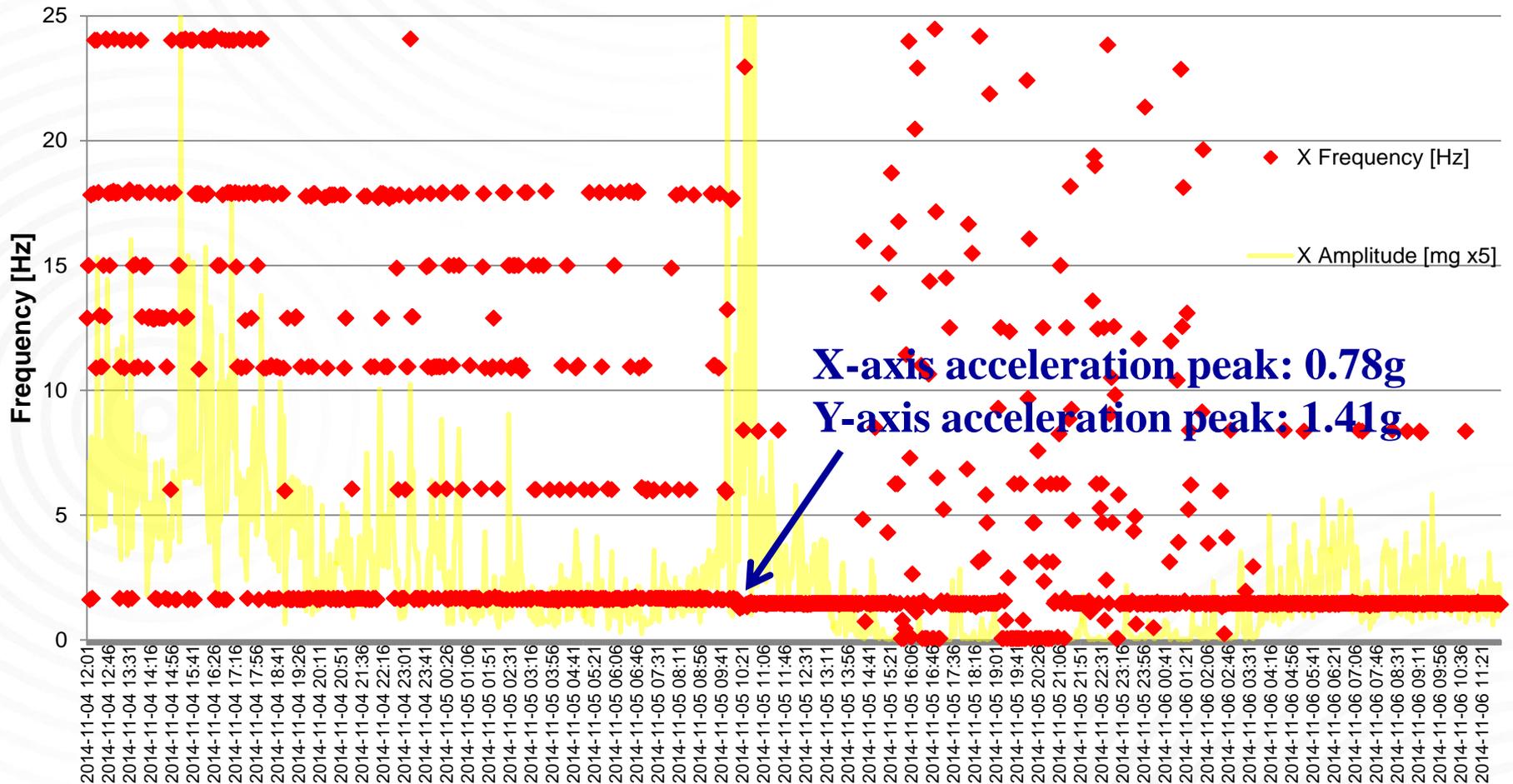


NCA02 AtoN platform acceleration and vibration magnitude peaks were recorded at 09:51

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# NCA02 Collision Test Results of 2014-11-05



Vibration profile of the NCA02 AtoN platform was changed permanently by the collision: **the X natural frequency shifted from 1.66 Hz to 1.46 Hz**, higher frequency components changed

# Conclusions

- ⊙ Preliminary results of deployment of AtoN telematics controllers TelFiCon™ on the selected fixed AtoNs of the Norwegian Coastal Administration for SHM are useful

Application of fixed AtoN Structural Health Monitoring as described **increases navigational safety and optimizes corrective maintenance costs** by comprehensive watch:

- ⊙ platform **inclination angles** (two alarm thresholds)
- ⊙ horizontal and vertical **acceleration vector magnitudes**
- ⊙ **amplitudes** of dominant components of vibration spectra (two thresholds) with immediate and detailed FFT analysis
- ⊙ **frequency** of the dominant spectral component
- ⊙ **collision events** detected even at TelFiCon™ standby

# Additional Information

Information on this AtoN Structural Health Monitoring project and associated technology can be requested from:

Mr Per Erik Ose, [per.erik.ose@kystverket.no](mailto:per.erik.ose@kystverket.no)

Mr Leif Arne Larsen, [leif.arne.larsen@kystverket.no](mailto:leif.arne.larsen@kystverket.no)

Mr Aivar Usk, [aivar.usk@cyber.ee](mailto:aivar.usk@cyber.ee)

